WEST Search History

Hide Items Restore Clear Cancel

DATE: Tuesday, November 16, 2004

Hide?	<u>Set</u> Name	Query	<u>Hit</u> Cour
	DB=I	PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ	
	L5	L4	
	L4	11 and (12 or L3)	
	L3	"relative rotation angle"	64
	L2	"relative rotation"	7163
	L1	(5669150 5065337 4907937 4483074 6570356 4806068 5214400 5867631 5294970 5963711 5222198 4323408 4384913 4422602 4557788 5425616 5511931 6240198 6243106 5642468 5190333 6003400 5646413 5844247 6051843 6141108 6347060 6380941 6462491 4814994 5314293 4842296 4549683 4629860 4878688 4925207 5311957 4831547 4512056 4244625 4266747 4268961 4381827 4396344 4756547 4996794 5016767 5257992 5265489 5304174).pn.	10

END OF SEARCH HISTORY



Principle of superposition in design of feedback control signals for dexterous multi-fingered robot hands

Arimoto, S.;

Science and Technology, 2000. KORUS 2000. Proceedings. The 4th Korea-Russia International Symposium on , Volume: 3 , 27 June-1 July 2000

Page(s): 49 -60 vol. 3

A method of ultrasonic sensor data integration for floorplan recognition

Ko, J.; Kim, W.; Chung, M.;

Intelligent Control, 1993., Proceedings of the 1993 IEEE International Symposium on , 25-27 Aug. 1993

Page(s): 346 -351

Motion planning for a redundant manipulator by genetic algorithm using an evaluation function extracted from skilled operators

Shibata, T.; Abe, T.; Tanie, K.; Nose, M.;

Fuzzy Systems, 1995. International Joint Conference of the Fourth IEEE International Conference on Fuzzy Systems and The Second International Fuzzy Engineering Symposium., Proceedings of 1995 IEEE International Conference on , Volume: 2 , 20-24 March 1995 Page(s): 883 -888 vol.2

Stochastic fuzzy servo control using multiple linear dynamic models

Watanabe, K.; Izumi, K.; Fuha Han;

Knowledge-Based Intelligent Electronic Systems, 1998. Proceedings KES '98. 1998 Second International Conference on , Volume: 3 , 21-23 April 1998

Page(s): 474 -482 vol.3

Simulation study of PD robot Cartesian control

Lin, S.-K.;

Robotics and Automation, 1989. Proceedings., 1989 IEEE International Conference on , 14-19 May 1989

Page(s): 1221 -1226 vol.2

Gravity based autonomous calibration for robot manipulators

Donghai Ma; Hollerbach, J.M.; Yangming Xu;

Robotics and Automation, 1994. Proceedings., 1994 IEEE International Conference on , 8-13 May 1994

Page(s): 2763 -2768 vol.4

A new sensing scheme for 3D active antenna

Kanayama, N.; Kaneko, M.; Tsuji, T.;

Multisensor Fusion and Integration for Intelligent Systems, 1996. IEEE/SICE/RSJ International Conference on , 8-11 Dec. 1996

Page(s): 597 -602

A robust eigenspace method for high-speed massively parallel vision systems

Mukai, T.; Ohnishi, N.;

Intelligent Robots and Systems, 1998. Proceedings., 1998 IEEE/RSJ International Conference on , Volume: 3 , 13-17 Oct. 1998

Page(s): 1795 -1800 vol.3

Automatic map generation with mobile robot

Matsuo, T.; Tanaka, K.; Abe, N.;

Systems, Man, and Cybernetics, 1999. IEEE SMC '99 Conference Proceedings. 1999 IEEE

International Conference on Volume: 4, 12-15 Oct. 1999

Page(s): 680 -685 vol.4

Sensor fusion and calibration for motion captures using accelerometers

Jihong Lee; Insoo Ha;

Robotics and Automation, 1999. Proceedings. 1999 IEEE International Conference on , Volume:

3, 10-15 May 1999

Page(s): 1954 -1959 vol.3

Neighborhood equilibrium grasp for multiple objects

Harada, K.; Kaneko, M.;

Robotics and Automation, 2000. Proceedings. ICRA '00. IEEE International Conference on,

Volume: 3, 24-28 April 2000

Page(s): 2159 -2164 vol.3

Existence of feedbacks from sensing to action for stable grasping and dexterous manipulation by multi-fingered robot hands

Arimoto, S.; Tahara, K.; Yamaguchi, M.;

Control Applications, 2001. (CCA '01). Proceedings of the 2001 IEEE International Conference

on , 5-7 Sept. 2001

Page(s): 524 -529

Singularity of nonlinear feedback control scheme for robots

Lin, S.K.;

Systems, Man and Cybernetics, IEEE Transactions on , Volume: 19 Issue: 1 , Jan.-Feb. 1989

Page(s): 134 -139

Analysis of camera movement errors in vision-based vehicle tracking

Sohn, W.; Kehtarnavaz, N.D.;

Pattern Analysis and Machine Intelligence, IEEE Transactions on , Volume: 17 Issue: 1 , Jan.

1995

Page(s): 57 -61

Active antenna for contact sensing

Kaneko, M.; Kanayama, N.; Tsuji, T.;

Robotics and Automation, IEEE Transactions on , Volume: 14 Issue: 2 , April 1998

Page(s): 278 -291

Copyright © 2003 IEEE -- All rights reserved